## CAME i-

## Swing-gate operator

## Came S.p.a.

indirizzo / address / adresse / adresse / direcciòn / endereço / adres / adres Via Martiri della Libertà 15-31030 Dosson di Casier, Treviso - Italy

DICHIARA CHE L'AUTOMAZIONE PER CANCELU A BATTENTE / DECLARES THAT THE DRIVE FOR SWING GATE ERK ART DASS DIE AUTOMATISIERUNG FUR FLUGELTORE / DECLARE QUE LE AUTOMATISATION POUR PORTALLS A BATTANTS / DECLARA QUE LAS AUTOMATIZACION PARA PUERTAS BATIENTES / DECLARA QUE AS AUTOMATZACOES PARA PORTOES A BATENTE/OSWADCZA ZE AUTOMATYKA DO BRAM SKRZYDLOWYCH / VERKL MART DAT DE AUTOMATISERING VOOR DRANHEKKEN

## FTX20DGC FTX20DLC

E' CONFORME ALLE DISPOSIZIONI DELE SEGUENTI DREITIVE/IT COMPLES WIH THE PROMSIONS OF THE FOUOWING DIRECTIVES/DEN VORGABEN DER FOLGENDEN RICHILINIEN ENTSPRECHEN /IL EST CONFORIMES AUX DISPOSIIONS DES DIRECTMES SUIVANTES / CUMPLEN CON LAS DISPOSICICNES DE LAS SIGUIENTES DIRECTNAS / ESTAOO DE ACORDO COM AS DISPOSICOEES DAS SEGUINIES DIRECTNAS / SA ZGODNE Z POSTANOMENIAMI NASTEPUJACYCH DYREKTYW EUROPEISKCH / VOLDOEN AAN DE VOORSCHRIFIEN VAN DE VOL GENDE RICHTL LINEN:

- COMPATIBILITA' ELEITROMAGNETICA / ELECTROMAGNETIC COMPATIBILTY / ELEKTROMAGNETISCHE VERTRAGGLICHKEIT / COMPATIBILITE ELECTRQMAGNETIQUE / COMPATIBILIDAD ELECTROMAGNEIICA /COMPATIEILIDADE ELEIROMAGNÉTICA / KOMPATYBILNOSCI ELEKTROMAGNETYCZNEJ / ELEKTROMAGNETISCHE COMPATIBILITEIT : 2014/30/UE.

Fiferimento norme armonizzate ed altre norme tecniche / Refer to European regulations and other technical regulations / Harmonislerte Bozugsnormen und andere technische Vorgaben / Ráférence aux normes harmonisées et aux autres normes techniques / Referencla normas armonizadas y otras normas técnicas / Reteréncia de normas harmonizatechniczne / Gehermonisearde en andere techriocho normen waarnaar is verwezen

EN 61000-6-2:2005
EN 61000-6-3:2007+A1:2011
EN 62233:2008
EN 60335-1:2012+A11:2014
EN 60335-2-103:2015

FISPEITA I REQUISTI ESSENZIALI APPUCATI: / MEET THE APPLICABLE ESSENTLAL REQUREMENTS: / DEN WESENTUCHEN ANGEWANDTEN ANFORDERUNGEN ENTSPRECHEN: /RESPECTENT LES CONDTIONS REQUISES NECESSAIRES APPLIQUEES: ANGEWANDIENANFORDERUNGEN ESENPRECHEN:/RESPECTENT SPELNIAJA PODSTAWOWE WYMAGANE WYRUNEI: / VOLDOEN AAN DE TOEPASEARE MINIMUM EISEN:
1.1.3; 1.1.5; 1.2.1; 1.2.2; 1.3.2; 1.3.7; 1.3.8.1; 1.4.1; 1.4.2; 1.5.1; 1.5.6; 1.5.8; 1.5.9; 1.5.9; 1.5.13; 1.6.1; 1.6.3; 1.6.4;
1.7.1; 1.7.2; 1.7.4

PERSONA AUTORZZATA A COSTITURE LA DOCUMENTAZIONE TECNICA PERTINENTE / PERSON AUTHORISED TO COMPIE THE RELE/ANT TECHNLCN DOCUMENTATION/ PERSON DIE BEVOUMAZCHIGT IST, DE RELEVANTEN TECHNISCHENUNIERLAGEN ZUSAMMENZUSTELEN / DOCUMENTATON TECHNICUE SPECIFIOUE DYATORISATON
 PERTINENTE / OSOEA UPOWAZNIONA DO ZREDAGONGNU DOF

CAME S.p.a.
La documentaxione tecrica pertinente è stata complata in confornta alraliggato VIIB. / The pertinent technical documentation has beon drawn up in complance with attached documont VIB. / De relevante technische Dokumentation wurde entsprechend dar Anlage VB a susgesteti. / La documentation technique spfecloque a étó remplie conformément à l'annexe IIB/La documentación técrica pertinente ha sido rellenada en cumplimerto con el anexo VIB. / A documentaçalo técrica pertinente fol preenchida do acordo corn o anexo viB. / Odnosna doiumentacja techriczna zostala zredagowana zgodnie z zalscrildem VIB, / De tochnische documentatio terzaka is opgesteld in overeenstemming met de biloge ViB.
CAME S.p.a. si impegna a trasmettere, in repposta a una richlesta adeguatamente motivata delfo autorta razional, informazioni pertinenti sule quasi maccinine, e/ Came S.pA, folowing a duly molivated request from the national authorities, undertakes to provide information relsted to the quasi machines. and / Die Fima Came Sp.A. vurpulchtet sich aud eine angemessen
 blen fondée da la part des autoaibs nationalas, les renseignements rebatits aux quasi machines / Came S.p.A se compromete a transmiti, como respuesta a una solicilud adecuadameme

 nievikonczorych nationsle autorteten de relevarte informatie voor de niet votooide machine to vosirekken,

## VIETA / FORBIDS / VERBIETET / INTERDIT / PROHIBE / PROIBE / ZABRANIA SIE / VERBIEDT

la messa in serdzjo finchè la mecchins finale in cui deve essere incorporata non è stata dichiarata conforme, se del caso alla 2006/42/CE. / commissioning of the above mentioned unti such moment when the final machine into which they must be incorporates, has been declared compliant, if petinent, to 2005/42/CE / Gie inbetriebnahme bevor die , Endmaschine" in die die unvolsilindige Maschine eingebsut wrd, als konlorm erkart wurde, gegebenenfals gemas der Richilive $2006 / 42 /$ EU. / la mise en service tant que la machine thale dans laquelle elle doit être incorporié n'a pas êé déclarde conforme, le cas echéant, a la norme 2006/42CE. I la puesta en sentcio hasta que la máquira thal en la que seda incorporada no haya sido doclarada

 procedura bya koriecza. / deze in weiking te stelen zolang de eindnachine wayin de niet votiooide machine moet worden ingubouwd in overeenstemming is verkaard, indien toepasselip met de richtilin 2006/42/EG.

Dosson di Casier (TV)
15 Gennaio / January / Januar / Janvier / Enero
/ janeiro / Styczen / Januari 2018
Legale Rappresentante / Legal Representative /Gesetzlicher Vertreter / Representant Legal / Representante Legal/ Representante Legal / Prawny Przedstawiciel / Juridische Vertegenwoordiger

Via Martiri della Libertà, 15-31030 Dosson di Casler - Treviso - Italy - Tel. (+39) 04224940 - Fax (+39) 04224941
Via Martiri della Liberta, 15-31030
info(eame.it - www.came.com
Cap. Soc. $1.610 .000,00 €$ - C.F. eP.L. 03481280265 - VAT IT 03481280265 - REATV 275359 - Reg Imp. TV 03481280265

B


## WHEN CLEANING, MAINTAINING AND REPLACING PARTS, DISCONNECT THE OPERATOR FROM THE MAINS POWER SUPPLY (EXCLUDING POINT B)

At least every six months, perform ordinary maintenance jobs.
$\triangle$ When performing this procedure, keep clear of the movement of the boom.
A - Wipe clean the photocells' glass with a soft, slightly water-dampened cloth. Do not use any solvents or other chemicals.
B - Check that the photocells are working properly by waving an object between them when the boom is moving: if the boom inverts its direction or the maneuver is stopped, the photocells are working properly.
C - Check that there are no impediments to the proper operation of the operator, such as any overgrown vegetation that could block the photocells or any changes or yielding to the barrier's structure.
Any repairs, or changes to the installation must be performed by qualified staff and all jobs logged carefully.

## WHAT TO DO IF ...

| ISSUES | POSSIBLE CAUSES | POSSIBLE FIXES |
| :--- | :--- | :--- |
| The operator <br> neither opens <br> nor closes | • Power supply is missing <br> • The gearmotor is stuck <br> signal or no no signal <br> - Release lever is raised | • Check main power supply <br> •Lock the gearmotor |
|  | - Button/s and/or selectors <br> stuck | - Make sure the release lever is lowered <br> - Cables are in proper working conditions |
| The operator <br> opens but <br> does not <br> close | - The photocells are working | - Check that there are no obstructions in the <br> range of operation of the photocells |

$\triangle$ If the problem cannot be solved by following the fixes in the table or if any malfunctions, anomalies, noises, vibrations or suspicious and unexpected behavior is experienced on the system, call for qualified assistance.

## $\triangle$ CAUTION! Important safety instructions. Follow all of these instructions. Improper installation can cause serious bodily harm. Before continuing, also read the general precautions for users.

This product must oniy be used for its specifically intended purpose. Any other use is dangerous. Came S.P.A. is not lable for any damage caused by improper, wrongrul and uneeasonable use. • This manual's product is defned by machinery directive 2006/42/CE as "Pariv-completed machnery". Partly-completed machnery is a set that almost constitutes a machine, but which, alone, cannot ensure a clearly defned applcation. Partiv-completed machinery is only destined to be incorpobated OR ASSEMBLED TO OTHER MACHNEEY OR OTHER PARTLY-COMPLLETED MACHNEERY OR APPARATUSES TO BULD machineery that is regulated by Driective 2006/42/CE. The fnal instalation must be complant with European difectue 2006/42/CE and European reference standards: EN 13241-1, EN 12453, EN 12445 ed EN 12635 . - Given these considerations, all procedures stated in this manual must be exclusively performed by expert, qualfife staff. • Laying the cables, installaton and testing must follow state-of-the-art procedures as dictated by regulations Before nstalling the operator, check that the gate is in proper mechancal conotion, that it is properly balanced and that it properily closes: If any of these conotions are not met, do not contine before having met all safety requirements. - The opebator cannot be used with gates fitted with pedestrian doors, unless its opebation can be activated onyy when the pedestrian door is in safety position. - Make sure that people cannot bet entrapped between the gate's moving and fxed parts due to the gate's movement. • Do not fit the operator upside down or onto elements that colld yeld to its welght. If necessary, add rennforcements to the fastenng points - check that the temperature range appearing on the operator is sutted to the place of instalation - Do not install door or gate leaves on tluted surfaces - check that no lawn watering dences spray the operator with water from the bottom up - Sutably section off and demarcate the entre installaton ste to prevent unauthorized persons from entering the area, Especially minors and chlldren. • Use proper protections to preveent mechancal hazards when people are lotering around the machinery's range of Action, for example, prevent crushing of fngers between the drive shaft and the mechancal stops, prevent criushing when the gate is opening, and so on. - Any residual risks must be nodicated Clearly with proper signage affxed in visibe areas. All of which must be explaned to end users.

- Affix cautionary signs, such as the gate plate, wherever needed and in plan sight the gate plate, wherever needed and in plain sight. • All openng controls must be nstalled at least 1.85 m from the perimeter of the gate's working area, or where they cannot be reached from outside the gate. - If the operator is installed lower than 2.5 from the ground or from any other access level, fit any protections and signs to prevennt hazardous stuations. - Make sure that mechancal stops afe already nstalled • Make sure the operator is nsstalled onto a sturdy surface that is protected from any collisions •Unless the key-operation is functionng (for e.g. kevpad selector, key-switch Selector, transponder selector, and so on), any mantanned-actoon control devices must be installed at least 1.5 m from the ground and out of reach from unauthorized users. - The manufacturer declines any lablity for using non-original products; which would result in warranty loss • All SwTCHES IN MAINTANED ACTION MODE MUST BE POSTTINEED SO THAT THE MOVING GATES Leaves, the transit AREAS AND vEHCLLE THRu-ways ARE COMPleteliv visible, and yet the Swiches must be also away from
any moving parts - Affix a permanent tag, that describes how to use the manual release mechanism, close to the mechanism. - Before handing over to users, check that the system is complant with the 2006/42/CE uniformed Machinery Directive. Make sure the settings on the operator are all SUITABLE AND THAT ANY SAFETY AND PROTECTION DEVICES, AND ALSO THE MANUAL RELEASE, WORK PROPERLY. - If the power-supply cable is damaged, it must be immedately replaced by the manufacturer or by an authorized technical assistance center, or in any case, by qualified staff, to prevent any risk • During all phases of the installation make sure you have cut off the mains power source. - The electrical cables must run through the cable glands and must not touch any heated parts, such as the motor, transformer, and so on). • Make sure you have set up a sutable dual pole cut off device along the power supply that is compliant with the installation rules. It should completely cut off the power supply according to category III surcharge conditions. - Keep the section of this manual INSIDE THE TECHNICAL FOLDER ALONG WITH THE MANUALS OF ALL THE OTHER DEVICES USED FOR YOUR AUTOMATION system. Remember to hand over to the end users all the operating manuals of the products that MAKE UP THE FINAL MACHINERY.

The next figure shows the main hazard points for people.


DO NOT TRANSIT THROUGH DURING MANEUVERING.


## KEY

[1] This symbol shows which parts to read carefully.
$\triangle$ This symbol shows which parts describe safety issues
This symbol shows which parts to tell users about.
The measurements, unless otherwise stated, are in millimeters.

## DESCRIPTION

Operator complete with control board, movement control and obstruction detecting device plus mechanical endstops for swing gates with leaves up to 2 m .

## INTENDED USE

This operator is designed to power swing gates for residential and apartment block use.
In Any installation and/or use other than that specified in this manual is forbidden.
LIMITS TO USE

$\triangle$ We suggest you always fit an electrolock onto swing gates for a more reliable closure.

## DIMENSIONS



## DESCRIPTION OF PARTS

1. Cover
2. Control-board protective cover
3. EMCO2 card
4. Post brace
5. Gearmotor
6. Mechanical stops
7. Release lever
8. Lock
9. Control-board supporting structure
10. Control-board supporting plate
11. ZL65 control board
12. Transmission arm protection
13. Transmission arm
14. Joint arm
15. Gate brace
16. Release keys
17. Release shaft for optional, pull-cord device

|  | UNI 5931 M8 x 80 | 2 |
| :---: | :---: | :---: |
|  | UNI 5931 M8 x 20 | 2 |
| 目 | UNI 5739 M10 x14 | 1 |
|  | UNI 5739 M6 x 10 | 2 |
| d | UNI 6955 3,9 $\times$ 9,5 | 1 |
|  | UNI 6955 3,9 $\times 13$ | 1 |
| (0) | $\emptyset 10 \times 39$ | 1 |
|  | UNI 6593 Ø 6 | 2 |
|  | UNI 6592 Ø 12 | 1 |
| S | $010 \times 45$ | 1 |
| 9 | $\emptyset 12 \times 26$ | 1 |
| (8) | UNI 7474 M8 | 2 |
|  | UNI 5588 M8 | 2 |


(4)

14)



| Model | FTX20DGC - FTX20DLC |
| :---: | :---: |
| Protection rating (IP) | 44 |
| Power supply (V-50/60 Hz) | 230 AC |
| Input voltage motor (V) | 24 DC |
| Max draw (A) | 4 |
| Stand-by consumption (W) | 7 |
| Stand-by consumption with the RGP1 (W) module | 0.5 |
| Maximum power (W) | 140 |
| Cycles/hour | 40 |
| Operating temperature ( ${ }^{\circ} \mathrm{C}$ ) | -20 to +55 |
| Torque (Nm) | 180 |
| Opening time at $90^{\circ}(\mathrm{s})$ | from 20 to 30 |
| Gear ratio | 1/1680 |
| Apparatus class | \| |
| Acoustic pressure dB (A) | $\leq 70$ |
| Weight (Kg) | 10.5 |

## STANDARD INSTALLATION

1. Operator
2. Gearmotor
3. Flashing light
4. Key-switch selector
5. Photocells
6. Photocells post
7. Mechanical gate stop
8. Junction pit
9. Transmitter


## GENERAL INSTALLATION INDICATIONS

## PRELIMINARY CHECKS

$\triangle$ Before beginning the installation, do the following:

- check that the gate structure is sturdy enough, the hinges work efficiently and that there is no friction between the fixed and moving parts;
- if ground stops are not, or cannot be, fitted, use the supplied mechanical stops;
- make sure that the point where the gearmotor is fastened is protected from any impacts and that the surface is solid enough;
- set up suitable tubes and conduits for the electric cables to pass through, making sure they are protected from any mechanical damage.

CABLE TYPES AND MINIMUM THICKNESSES

| Connection | cable length |  |
| :---: | :---: | :---: |
|  | <20 m | 20<30 m |
| Input voltage for 230 V AC control board ( $1 \mathrm{P}+\mathrm{N}+\mathrm{PE}$ ) | $3 \mathrm{G} \times 1.5 \mathrm{~mm}^{2}$ | $3 \mathrm{G} \times 2.5 \mathrm{~mm}^{2}$ |
| 24 V DC gearmotor | $3 \times 1.5 \mathrm{~mm}^{2}$ | $3 \times 2.5 \mathrm{~mm}^{2}$ |
| Electric lock | $2 \times 0.5 \mathrm{~mm}^{2}$ |  |
| Flashing light | $2 \times 0.5 \mathrm{~mm}^{2}$ |  |
| Command and control devices | $2 \times 0.5 \mathrm{~mm}^{2}$ |  |
| TX Photocells | $2 \times 0.5 \mathrm{~mm}^{2}$ |  |
| RX photocells | $4 \times 0.5 \mathrm{~mm}^{2}$ |  |

(1) When operating at 230 V and outdoors, use H05RN-F-type cables that are 60245 IEC 57 (IEC) compliant; whereas indoors, use H05VV-F-type cables that are 60227 IEC 53 (IEC) compliant. For power supplies up to 48 V , you can use FROR 20-22 II-type cables that comply with EN 50267-2-1 (CEI).
[al To connect the antenna, use the RG58 (we suggest up to 5 m ).
[a] For paired connection and CRP, use a UTP CAT5-type cable (up to 1,000 m long).
[a] If cable lengths differ from those specified in the table, establish the cable sections depending on the actual power draw of the connected devices and according to the provisions of regulation CEI EN 60204-1.

La] For multiple, sequential loads along the same line, the dimensions on the table need to be recalculated according to the actual power draw and distances. For connecting products that are not contemplated in this manual, see the literature accompanying said products

## INSTALLATION

$\triangle$ Only skilled, qualified staff must install this product.
$\triangle$ The following illustrations are mere examples in that the space for fastening the operator and accessories varies depending on the installation area. It is up to the fitter, therefore, to choose the most suitable solution.
1 The following figures show a standard installation with the gearmotor and transmission arms fitted to the left of the inward-opening gate. Fitting the gearmotor with the transmission arms to the right is done symmetrically. Careful! For outward opening gate leaves, follow the chapter titled "INSTALLING AND CONNECTING FOR OUTWARD OPENING".

## INITIAL WORKS

Fit junction boxes and corrugated tubing needed for the incoming connections from the distribution pit.
1 The number of tubes depends on the type of system and the accessories you are going to fit. You will need at least two corrugated tubes where the operator is installed (on the gate leaf that opens first).


CHECKING MEASUREMENTS AND APPLICATIVE DIMENSIONS
Establish where you will fit the gate brace and measure where the gate-post brace will fit. Make sure to respect the quotas shown in the drawing and table.


GATE BRACE


## FTX20DGC



FTX20DLC


Marked the spots where the gate-post brace and gate brace will be fitted.
(1) The fastening measurements are listed in the paragraph titled CHECKING MEASUREMENTS AND APPLICATIVE DIMENSIONS.
Drill the anchoring points, fit the dowels or use plugs that will hold fast the screws.
Ind The drawings are mere examples. Installers should carefully choose the most suitable set up according to the type and thickness of the gate leaf.


Remove the operator's cover in the following way: - open the lock protection cap, fit, the trilobe key into the lock and turn in counter-clockwise;

- turn the release lever and loosen the screw that fastens the cover to the gearmotor;
- push the cover back and lightly pull on its sides to lift it.

1


2


3


Fit the gearmotor into the gate-post brace and tighten the nuts and bolts.
Fit the plug into the socket on the gearmotor drive-shaft.


Fit the transmission arm to the shaft by using the slow-shaft washer and the bolt.


Fasten the driven-arm to the transmission arm by using the pin, the bolt and the washer.

$\triangle$ Warning! If no end stops are fitted, you must fasten the stops.
FASTENING THE MECHANICAL STOPS
Release the gearmotor.
When opening.
Entirely open the gate leaf. Fit the stop under the casing, against the transmission arm and fasten it with the bolt.


## When closing.

Close the leaf. Fit the second stop against the opposite side of the arm and fasten it with the bolt.


## ESTABLISHING THE LIMIT-SWITCH POINTS

With the gearmotor released and the gate-leaf closed, adjust the closing limit-switch grub screw by turning it clockwise or counterclockwise. Tighten the nut to fasten the grub-screw.


Likewise, adjust the endstop by turning the endless screw on the other endstop.


## CONTROL CARD

$\triangle$ Warning! Before working on the control panel, cut off the main power supply and, if present, remove any batteries.
All wiring connections are quick-fuse protected.

| Fuses | ZL65 |
| :--- | :---: |
| LINE - Line | $2 \mathrm{~A}-\mathrm{F}=230 \mathrm{~V}$ |
| ACCESSORIES - Accessories | $2 \mathrm{~A}-\mathrm{F}$ |

## DESCRIPTION OF PARTS

1. Terminals for signaling devices
2. Gearmotors with encoder terminals
3. Control devices terminals
4. Safety devices terminals
5. CRP connection terminals
6. Terminals for transponder devices
7. Keypad selector terminal
8. Antenna terminal
9. Module connector CONNECT GW
10. AF card connector
11. R700/R800 board connector
12. Connector for the RIO-CONN card
13. Memory Roll card connector
14. Display
15. Programming buttons
16. RSE board connector
17. Terminals for the RGP1 module
18. Accessories fuse
19. Power supply terminal board
20. Line fuse

$\triangle$ The electrical cables must not touch any heated parts such as the motor, transformer, and so on.


24 V AC/DC - max 40 W accessories
power-supply output


Trasformatore

WARNING! An electric lock must be fitted to gate leaves exceeding 2.5 m in length when using irreversible gearmotors. Electric locks must always be fitted when using reversible gearmotors.
Connect the electric lock to the transformer's 17 V output and to terminal 5 on the control board.
WARNING! To access the transformer, you will need to remove the control board brace.


SIGNALING DEVICES


Gate open signaling output
(Contact rated for: 24 V AC/DC - 3 W max.).
See function F 10.

Either flashing light or cycle light connection output (Contact rated for: 24 V AC/DC - 25 W max.).
See function F 18.

WARNING! For the system to work properly, before fitting any plug-in card, such as the AF or R800 one, you MUST CUT OFF THE MAINS POWER SUPPLY and, if present, disconnect any batteries.


Connector for UR042 module.
[1] The UR042 module will not work if the RGP1
module or the RSE card is connected.
 F8.

OPEN-CLOSE-INVERT function (step-step) from control device (NO contact). Alternatively, when programming the functions, you can activate the OPEN-STOP-CLOSE-STOP (sequential) command, OPEN or CLOSE. See function F7. OPEN, PARTIAL or PEDESTRIAN OPENING from a control device (NO contact). See function

STOP button (NC contact). For stopping the gate while excluding automatic closing. To resume movement press the control button or use another control device. See function F1.
If unused, it should be deactivated during programming.


Operator installed on the left (outer view).
(Default setting)


Operator installed on the right (inner view).


OPERATOR WITH GEARMOTOR


Operator fitted to the right and gearmotor to the left (inner view) with operator delayed when opening.



## SAFETY DEVICES

## Photocells

Configure contact CX or CY (NC), safety input for photocells. See CX input functions (Function F2) or CY (Function F3) in:

- C1 reopening during closing. When the gate is closing, opening the contact triggers the inversion of movement until the gate is fully open again;
- C2 close back up during opening. When the gate is opening, opening the contact triggers the inversion of movement until the gate is completely closed.
- C3 partial stop. Opening the contact triggers the gate to stop, if it is moving, and to shift into automatic closing (if the automatic closing function has been set);
- C4 obstruction wait. Opening the contact triggers the gate to stop, if it is moving, and to resume its movement once the obstruction is removed.
[1] If contacts CX and CY are not used they should be deactivated during programming.



## Sensitive Safety Edges

Configure contact CX or CY (NC), input for safety devices, such as sensitive safety edges, that comply with EN 12978 provisions.
See CX input functions (Function F2) or CY (Function F3) in:

- C7 reopening during closing. When the gate is closing, opening the contact triggers the inversion of movement until the gate is fully open again;
- C8 reclosing during opening. When the gate is opening, opening the contact triggers the inversion of movement until the gate is fully closed.
If If contacts CX and CY are not used they should be deactivated during programming.



## WIRELESS DEVICES

Fit the RIO-CONN card into the corresponding connector on the control board.
Set the function which is to be associated with the wireless device (F 65, F66, F 67 and F 68).
Configure the wireless accessories (see the folder of the accessory you want to configure).
ID If the devices are not configured with the RIO-CONN card, the E 18 error message is displayed.
$\triangle$ If the system has radiofrequency interferences, the wireless system will inhibit the operator's normal operating mode and the E 17 error message is displayed.



RIO-EDGE


RIO-CELL


RIO-LUX

RS485 serial connection with RSE card via CRP (Came Remote Protocol).


## PROGRAMMING

## DESCRIPTION OF THE PROGRAMMING COMMANDS

The ESC button is for:

- exiting menus;
- cancelling changes;
- stopping the gate (only when testing).


The ENTER key is for:

- entering menus;
- confirming or memorizing set values.

The $<>$ keys are for:

- moving from one item to another;
- increasing or decreasing a value;
- opening and closing the gate (only when testing).

10 To enter the ment keep ENTER key pressed for at least one second.


ID] To exit the menu, wait 10 seconds or press the ESC key.


## $\triangle$ When programming, the operator needs to be in stop mode.

NC input - Gate stop that excludes any automatic closing; to resume F1 Total stop [1-2] movement, use the control device. The safety device should be fitted into 1-2. If unused, select OFF.

## OFF (default) / ON

NC input - Can associate: C1 = reopening during closing by photocells, C2 $=$ reclosing during opening by photocells, C3 = partial stop, C4 = obstruction wait, $\mathrm{C7}=$ reopening during closing by sensitive safety-edges (with clean
F2 Input [2-CX]

F3 Input [2-CY]

F5 Safety test contact), $\mathrm{C} 8=$ reclosing during opening by sensitive safety-edges (with clean contact).
[1] The C3 Partial stop function only appears if the F 19 Automatic closing time function is activated.

## OFF (default) / C1 / C2 / C3 / C4 / C7 / C8

NC input - Can associate: C1 = reopening during closing by photocells, C2 = reclosing during opening by photocells, C3 = partial stop, C4 = obstruction wait, $\mathrm{C} 7=$ reopening during closing by sensitive safety-edges (with clean contact), $\mathrm{C} 8=$ reclosing during opening by sensitive safety-edges (with clean contact).
The C3 Partial stop function only appears if the F 19 Automatic closing time function is activated.
OFF (default) / C1 / C2 / C3 / C4 / C7 / C8
After every opening or closing command, the board will check whether the photocells are working properly.
[a] The safety test is always active for wireless devices.
OFF (default) / $1=C X / 2=C Y / 4=C X+C Y$
The gate opens and closes by keeping the button pressed. Opening button on contact 2-3P and closing button on contact 2-7. All other control devices, even radio-based ones, are excluded.

## OFF (default) / ON

From the control device connected to 2-7 it performs the step-step (open-

F7 Command [2-7]

F8 Command [2-3P]

Obstruction detection with motor stopped close-invert) or sequential (open-stop-close-stop) command.
$0=$ Step-step $($ default) $/ \mathbf{1}=$ Sequential $/ 2=$ Open / $3=$ Close
From the control device connected to 2-3P it executes the pedestrian opening (completely opens the M2 gate leaf) or partial opening (it partially opens the M2 gate leaf: the opening arc depends on the percentage of travel set up with F36).

## 0 = Pedestrian opening (default) / 1 = Partial opening / 2 = Open

With the gate closed, opened or totally stopped, the gearmotor stays idle if the safety devices, that is, photocells or sensitive safety-edges detect an obstruction.

| F10 | Output for gate open or for enabling the electric lock | It signals the gate status. The signaling device is connected to 10-5 or, alternatively, it enables the electric lock connected to the 17 V output of the transformer and to terminal 5. <br> $0=0 n$ when the barrier is open and moving (default) / 1= during openings it flashes intermittently each half second, and during closings it flashes intermittently each second. It stays on steadily when the barrier is open, off or when it s closed / 2 = electric lock is enabled |
| :---: | :---: | :---: |
| F11 | Encoder | Managing slow-downs, obstruction detections and sensitivity. 10. With this function deactivated, adjust the working time of function F22, in this way, the gearmotor perform maneuvers at slower speeds. <br> OFF / ON (default) |
| F12 | Soft Start | With each opening and closing command, the gate starts moving slowly for a few seconds. <br> OFF (default) / ON |
| F13 | Closing thrust | At the closing limit switch, the gearmotors make the leaves perform a brief closing thrust. <br> OFF (default) // 1 = minimum thrust $/ 2$ = medium thrust $/ 3$ |
| F14 | Sensor type | Setting the type of accessory for controlling the operator. <br> $0=$ command with transponder sensor or magnetic card reader / $1=$ command with keypad selector (default) |
| F16 | Stop Jolt | Before every opening or closing maneuver, the leaves thrust inwards to release the electric lock. The thrust time, is set with F 26. <br> OFF (default) / ON |
| F18 | Additional light | Output for connecting the additional light onto 10-E. <br> Flashing light: it flashes when the gate is opening and closing. <br> Cycle light: additional external light for increasing illumination in the drive way. It stays on from the moment the leaf starts opening until it again closes completely - including the waiting time before the automatic-closing time. $0 \text { = Flashing light ( default ) / } 1=\text { Cycle }$ |
| F19 | Automatic Closing Time | The automatic-closing wait starts when the opening limit switch point is reached and can be set to between 1 and 180 seconds. The automatic closing does not activate if any of the safety devices trigger when an obstruction is detected, or after a total stop, or during a power outage. <br> OFF (default) $/ 1=1$ second $/ . . . / 180=180$ seconds |
| F20 | Automatic closing time after pedestrian or partial openings | The wait before the automatic closing starts after a partial opening command for an adjustable time of between 1 s and 180 s . <br> The automatic closing does not activate if any of the safety devices trigger when an obstruction is detected, or after a total stop, or during a power outage. <br> OFF (default) $/ 1=1$ second $/ . . . / 180=180$ seconds |
| F21 | Pre-flashing time | Adjusting the pre-flashing time for the flashing light connected to 10-E before each maneuver. The flashing time is adjustable from one to ten seconds. |

OFF (default) $/ 1=1$ second $/ . . . / 10=10$ seconds
Motors working time, when opening and closing. Adjustable between five
F22 Operating time and 180 seconds.
$5=5$ seconds $/ \ldots / 120=120$ seconds $($ default $) / \ldots / 180=180$ seconds

| F23 | Delay in opening time | After an opening command, the M1 gearmotor starts delayed. The delay time is settable between one and ten seconds. |
| :---: | :---: | :---: |
|  |  | $0=$ Deactivated $/ \ldots / 2=2$ seconds (default) $/ \ldots / 10=10$ seconds |
| F24 | Closing delay time | After either a closing command or an automatic closing, the M2 gearmotor starts delayed. The delay time is adjustable between 1 and 25 seconds. $0=\text { Deactivated } / \ldots / 5=5 \text { seconds (default) } / . . . / 25=25 \text { seconds }$ |
| F26 | Closing thrust time | After an opening or closing command, the gearmotor thrusts inward for an adjustable time between one and two seconds. $1=1 \text { second }(\text { default }) / 2=2 \text { seconds }$ |
| F27 | Lock time | After an opening or closing command, the electric lock releases for an adjustable time between one and four seconds. $1=1 \text { second }(\text { default }) / \ldots / 4=4 \text { seconds }$ |
| F28 | Gate travel speed | Setting the gate's opening and closing speeds, calculated as a percentage. $60=60 \%$ of the maximum speed $/ \ldots / 100=100 \%$ of the maximum speed (default) |
| F30 | Slow-down speed | Setting the gate's opening and closing slow-down speed, calculated as a percentage. <br> $10=10 \%$ of the maximum speed $/ \ldots / 50=50 \%$ of the maximum speed (default) $/ \ldots / 60=60 \%$ of the maximum speed <br> For the FTX20DGC-series gearmotors, the slow-down speed is set between $15 \%$ and $60 \%$. |
| F33 | Calibration speed | Setting the gearmotors' speeds during calibration, calculated as a percentage. $20=20 \%$ of the maximum speed $/ \ldots / 50=50 \%$ of the maximum speed (default) / .../ $60=60 \%$ of the maximum speed |
| F34 | Travel sensitivity | Adjusting obstruction detection sensitivity during gate travel. $10 \text { = Maximum sensitivity / . . / } 100 \text { = Minimum sensitivity (default) }$ |
| F35 | Slow-down sensitivity | Adjusting obstruction detection sensitivity during slow-down. $10=$ Maximum sensitivity / . . / $100=$ Minimum sensitivity (default) |
| F36 | Adjusting the partial opening | Adjustment as a percentage of total travel, during gate opening. $\begin{aligned} & 10=10 \% \text { of the gate travel } / \ldots / 40=40 \% \text { of the gate travel }(\text { default }) / \ldots / \\ & 80=80 \% \text { of the gate travel } \end{aligned}$ |
| F37 | Opening slow-down point for the M1 motor | Adjustment as a percentage of total travel, of the beginning slow-down point of gearmotor M1 during opening. <br> Ta This function only appears if the Encoder function is activated. <br> $\mathbf{1}=1 \%$ of the gate travel $/ \ldots / 25=25 \%$ of the gate travel (default) $/ \ldots / 60$ <br> $=60 \%$ of the gate travel |
| F38 | Closing slow-down point of the M1 motor | Adjustment as a percentage of total travel, of the beginning slow-down point of gearmotor M1 during closing. <br> 110 This function only appears if the Encoder function is activated. <br> $1=1 \%$ of the gate travel $/ \ldots / 25=25 \%$ of the gate travel (default) $/ \ldots / 60$ <br> $=60 \%$ of the gate travel |
| F39 | Opening approach point of the M1 motor | Adjusting as a percentage of the total travel, the M1 motor's opening approach starting point. <br> Ma This function only appears if the Encoder function is activated. <br> $\mathbf{1}=1 \%$ of the gate travel $/ \ldots / 10=10 \%$ of the gate travel (default) |


| F40 | Closing approach point for motor M1 | Adjusting as a percentage of the total travel, the M1 motor's closingapproach starting point. <br> This function only appears if the Encoder function is activated. <br> $1=1 \%$ of the gate travel $/ \ldots / 10=10 \%$ of the gate travel (default) |
| :---: | :---: | :---: |
| F41 | Opening slow-down point for motor M2 | Adjusting as a percentage of the total travel, the M2 motor's opening slowdown starting point. <br> (1) This function only appears if the Encoder function is activated. <br> $1=1 \%$ of the gate travel $/ \ldots / 25=25 \%$ of the gate travel (default) $/ \ldots / 60$ $=60 \%$ of the gate travel |
| F42 | Closing slow-down point for motor M2 | Adjusting as a percentage of the total travel, the M2 motor's closing slowdown starting point. <br> 1 This function only appears if the Encoder function is activated. <br> $\mathbf{1}=1 \%$ of the gate travel $/ \ldots / 25=25 \%$ of the gate travel (default) $/ \ldots / 60$ $=60 \%$ of the gate travel |
| F43 | Opening approach point for motor M2 | Adjusting as a percentage of the total travel, of the M2 motor's opening approach starting point. <br> ID. This function only appears if the Encoder function is activated. <br> $1=1 \%$ of the gate travel $/ \ldots / 10=10 \%$ of the gate travel (default) |
| F44 | Closing approach point for motor M2 | Adjusting as a percentage of the total travel, the M2 motor's closing approach starting point. <br> 1 This function only appears if the Encoder function is activated. <br> $1=1 \%$ of the gate travel $/ \ldots / 10=10 \%$ of the gate travel (default) |
| F46 | Number of motors | For setting the number of motors connected to the control panel. OFF = M1 and M2 (default) / ON = M2 |
| F49 | Managing the serial connection | For enabling the CRP (Came Remote Protocol). OFF / 3 = CRP (default) |
| F50 | Saving data | Saving users and saved settings in memory roll. <br> 1 This function only appears if a memory roll has been fitted into the control board. OFF (default) / ON |
| F51 | Reading of data | Uploading data saved in memory roll. <br> In This function only appears if a memory roll has been fitted into the control board. <br> OFF (default) / ON |
| F56 | Peripheral number | To set the peripheral's number from 1 to 255 for each control board when you have a system with several operators. $1 \text {----> } 255$ |
| F63 | COM speed | For setting the communication speed used in the CRP (Came Remote Protocol) connection system. <br> $0=1200$ Baud $/ 1=2400$ Baud $/ 2=4800$ Baud $/ 3=9600$ Baud $/ 4=$ 14400 Baud $/ 5=19200$ Baud $/ 6=38400$ Baud (default) $/ 7=57600$ Baud $/ 8=115200$ Baud |


| F65 | Wireless input RIO-EDGE [T1] | Wireless (RIO-EDGE) safety device associated to a function chosen among those available: P0 = TOTAL STOP, P7 = reopening during closing, P8 = reclosing during opening. <br> For programming, see the instructions that come with the accessory. <br> Ta This function only appears is the control board has been fitted with a RIO-CONN card. <br> OFF (default) / PO / P7 / P8 |
| :---: | :---: | :---: |
| F66 | Wireless input RIO-EDGE [T2] | Wireless (RIO-EDGE) safety device associated to a function chosen among those available: P0 $=$ TOTAL STOP, P7 $=$ reopening during closing, $\mathrm{P} 8=$ reclosing during opening. <br> For programming, see the instructions that come with the accessory. <br> 1 This function only appears is the control board has been fitted with a RIO-CONN card. <br> OFF (default) / PO / P7 / P8 |
| F67 | Wireless input RIO-CELL [T1] | RIO-CELL is associated to any function chosen among those available: $\mathrm{P} 1=$ reopening during closing; P2 = reclosing during opening; P3 = partial stop; P4 = obstruction wait. <br> For programming, see the instructions that come with the accessory. <br> Ia This function only appears is the control board has been fitted with a RIO-CONN card. <br> OFF (default) / P1 / P2 / P3 / P4 |
| F68 | Wireless input RIO-CELL [T2] | RIO-CELL is associated to any function chosen among those available: $\mathrm{P} 1=$ reopening during closing; $\mathrm{P} 2=$ reclosing during opening; $\mathrm{P} 3=$ partial stop; P4 = obstruction wait. <br> For programming, see the instructions that come with the accessory. <br> Ind This function only appears is the control board has been fitted with a RIO-CONN card. <br> OFF (default) / P1 / P2 / P3 / P4 |
| U1 | Entering users | Entering up to 250 users and associating to each one a function of choice among those included. Add users via a transmitter or other control device (see the paragraph called ADDING USERS WITH AN ASSOCIATED COMMAND). <br> 1 = Step-step command (open-close) / 2 = Sequential command (open-stop-close-stop) / 3 = Only open command / 4 = Partial command |
| U2 | Deleting users | Deleting a single user <br> OFF / ON = Enabling the deletion of single users. |
| U3 | Deleting users | Deleting all users. OFF / ON = Delete all users |
| U4 | Decoding the code | Select the type of transmitter radio coding that you wish to save on the control board. <br> $\triangle$ When you select a radio coding, all saved transmitter are automatically deleted. <br> The TWIN coding lets you save multiple user with the same key (Key block). $1 \text { = all (default) / } 2 \text { = Rolling Code } / 3=\text { TWIN }$ |
| A1 | Motor type | For setting the type of gearmotor fitted onto the system. 1 = SWN20 - SWN25 (default) / 2 = FA7024CB / 3 = FTX20DGC |


| A2 $\quad$ Motors test | Test for checking the gearmotors' proper rotating directions (see the MOTORS <br> TEST paragraph). <br> OFF / ON |
| :--- | :--- | :--- |
| Calibrating the gate travel (see the paragraph called CALIBRATING THE GATE |  |
| TRAVEL). |  |
| (Cal This function appears only is the Encoder function is activated. |  |
| OFF / ON |  |

## SETTING UP

Once the electrical connections are complete, have skilled staff commission the operator.
Before continuing, make sure the area is free of any obstructions, and that there are mechanical, opening and closing gate stops in place.
Power up and begin configuring the system. Important! Start programming by first doing the following functions:

- type of motor (A1);
- number of motors (F46);
- motors test (A2), see the specific paragraph;
- travel calibration (A3), see the specific paragraph.

Once the programming is done, verify that the operator and all the accessories are working properly. Use the $<>$ keys to open and close the gate, and the ESC key to stop it.
$\mathbb{L D}$ After powering up the system, the first maneuver is always the opening. In this phase, the gate cannot be closed. You will need to wait for the gate to completely open.
$\triangle$ Immediately press the STOP button if any suspicious malfunctions, noises or vibrations occur in the system.
10.1 Commissioning should be done also after each restoring procedure (A4).

Select A2. Press ENTER to confirm. (1)
Select ON. Press ENTER to confirm the motors test procedure. (2)
The following [---] characters will be displayed while waiting for a command. (3)
Keep pressed the > key and check whether the M2 second gearmotor's leaf performs an opening maneuver.
[1] If the leaf performs an opening maneuver, invert the motor's phases. (4)
Perform the same procedure using the < arrow key to check the M1 first gearmotor's leaf.
Ial If the leaf performs an opening maneuver, invert the motor's phases.


## TRAVEL CALIBRATION

Before calibrating the gate travel, position the gate half-way, check that the maneuvering area is clear of any obstruction and check that there are mechanical opening and closing stops.
$\triangle$ The mechanical end-stops are obligatory.
Important! During calibration, all safety devices will be disabled.
Select A3. Press ENTER to confirm. (1)
Select ON. Press ENTER to confirm the automatic travel calibration procedure.2
The first gearmotor leaf will perform a closing maneuver until the closing strike
... then, the second gearmotor leaf will perform the same maneuver ... (4)
... the the second gearmotor's leaf will perform an opening maneuver until the closing strike
5
... the first gearmotor's leaf will perform the same maneuver. (6)

1

(3)


5

(2)


## MANAGING USERS

ID. When adding and deleting users, the flashing numbers appearing are those numbers that are available and usable to assign to a new user (max. 250 users).
LD Before registering the users, make sure the AF radio card is plugged into the connector (see the paragraph called CONTROL DEVICES).

## ENTERING A USER WITH AN ASSOCIATED COMMAND

Select U1. Press ENTER to confirm. (1)
Select a command to associate to the user.
The commands are:

- 1 = step-step (open-close);
- 2 = sequential (open-stop-close-stop);
- 3 = open;
-4 = partial opening.
Press ENTER to confirm... 2
... a number between 1 and 250 will start flashing for a few seconds.
Send the code from the transmitter or other control device, such as, a keypad selector or a transponder. 3 [D] Note down, the registered users, in the "REGISTERED USERS LIST".

1


2


3


| 1 | 11 | 21 |
| :---: | :---: | :---: |
| 2 | 12 | 22 |
| 3 | 13 | 23 |
| 4 | 14 | 24 |
| 5 | 15 | 25 |
| 6 | 16 | 26 |
| 7 | 17 | 27 |
| 8 | 18 | 28 |
| 9 | 19 | 29 |
| 10 | 20 | 30 |



| 127 | 159 | 191 |  |
| :---: | :---: | :---: | :---: |
| 128 | 160 | 192 |  |
| 129 | 161 | 193 |  |
| 130 | 162 | 194 |  |
| 131 | 163 | 195 |  |
| 132 | 164 | 196 |  |
| 133 | 165 | 197 |  |
| 134 | 166 | 198 |  |
| 135 | 167 | 199 |  |
| 136 | 168 | 200 |  |
| 137 | 169 | 201 |  |
| 138 | 170 | 202 |  |
| 139 | 171 | 203 |  |
| 140 | 172 | 204 |  |
| 141 | 173 | 205 |  |
| 142 | 174 | 206 |  |
| 143 | 175 | 207 |  |
| 144 | 176 | 208 |  |
| 145 | 177 | 209 |  |
| 146 | 178 | 210 |  |
| 147 | 179 | 211 |  |
| 148 | 180 | 212 |  |
| 149 | 181 | 213 |  |
| 150 | 182 | 214 |  |
| 151 | 183 | 215 |  |
| 152 | 184 | 216 |  |
| 153 | 185 | 217 |  |
| 154 | 186 | 218 |  |
| 155 | 187 | 219 |  |
| 156 | 188 | 220 |  |
| 157 | 189 | 221 |  |
| 158 | 190 | 222 |  |


| 223 | 233 | 243 |
| :--- | :--- | :--- |
| 224 | 234 | 244 |
| 225 | 235 | 245 |
| 226 | 236 | 246 |
| 227 | 237 | 247 |
| 228 | 238 | 248 |
| 229 | 239 | 249 |
| 230 | 240 | 250 |
| 231 | 241 |  |
| 232 | 242 |  |

## DELETING SINGLE USERS

Select U 2. Press ENTER to confirm. 1
Select ON. Press ENTER to confirm the deletion procedure. (2)
Use the arrow keys select the number of the user you wish to delete.
Press ENTER to confirm. 3
... CLr will appear on the screen to confirm deletion.


For saving user and system configuration data with the Memory Roll, and for then reusing them on another control board, even on fitted into another system.
WARNING! Fitting and extracting the Memory Roll must be done with the mains power disconnected.
Fit the Memory Roll into the its corresponding connector on the control board.
Select F50. Press ENTER to confirm. (2)
Select ON. Press ENTER to confirm the data saving procedure. 3
Extract the Memory roll and fit it into the connector of another control board.
Select F51. Press ENTER to confirm. (5)
Select ON. Press ENTER to confirm the data uploading procedure.(6

(4)




6


## ILLUSTRATION OF THE SLOW-DOWN POINTS AND END-STROKE AREAS

ID. The travel areas and slow-down and approach points are tested to comply with the parameters set forth by Technical Regulations EN 12445 and EN 12453 for impact force compatibility of moving gate leaves.

$A=$ Movement area at normal speed.
$B^{*}=$ Movement area at slowed-down speed.
C = Encoder intervention zone with movement inversion.
D = Encoder intervention zone with movement stopped.
$\mathrm{E}=$ Opening slow-down starting point for M2.
$\mathrm{F}=$ Closing slow-down starting point for M2.
$\mathrm{G}=$ Opening slow-down starting point for M1.
$\mathrm{H}=$ Closing slow-down starting point for M1.
$\left.\right|^{* *}=$ Closing approach starting point for M2.
$L^{* *}=$ Closing approach starting point for M1.
$\mathrm{M}^{\star *}=$ Opening approach starting point for M 2 .
$\mathrm{N}^{* *}=$ Opening approach starting point for M1.
$0=$ Strike plates..

* Minimum 600 mm from the strike plate.
** Set the closing-rest percentage for function F $39-$ F 40 for the first motor (M1) and F43-F44 for the second motor (M2) so as to achieve a distance of less than 50 mm from the strike plate.


## FINAL OPERATIONS

## FASTENING THE COVER

Once the electrical connections and set up are done, fit the cover and fasten it using the supplied screws, then reposition the release lever.


## FASTENING THE TRANSMISSION ARM PROTECTION

Fit the protection under the operator and fasten it to the transmission arm using the screw.


## ERROR MESSAGE

[] The error messages are shown on the display.

| E1 | The travel calibration was interrupted when the STOP button was activated |
| :--- | :--- |
| E2 | Calibrating the complete gate-travel |
| E3 | Encoder broken |
| E4 | Services test error |
| E7 | Insufficient working time |
| E9 | Closing obstruction |
| E10 | Opening obstruction |
| E11 | Maximum number of detected obstructions |
| E14 | Serial communication error |
| E15 | Incompatible transmitter error |
| E17 | Wireless system error |
| E18 | The wireless system is not configured |

## INWARD OPENING CONNECTIONS AND INSTALLING

Following, are the only things that change compared to a standard installation:

## CHECKING MEASUREMENTS AND APPLICATIVE DIMENSIONS

Establish where you will fit the gate brace and measure where the gate-post brace will fit. Make sure to respect the quotas shown in the drawing and table.


| Leaf opening arc $\left({ }^{\circ}\right)$ | A | B | C max |
| :--- | :---: | :---: | :---: |
| 90 | 140 | 420 | 60 |
| 110 | 140 | 420 | 60 |

$\triangle$ Warning! If no end stops are fitted, you must fasten the stops.

## FASTENING THE MECHANICAL STOPS

Release the gearmotor.

## When opening.

Entirely open the gate leaf. Fit the stop below the casing, against the transmission arm and fasten it by using the bolt.



## When closing.

Close the leaf. Fit the second stop against the opposite side of the arm and fasten it with the bolt.


## ESTABLISHING THE LIMIT-SWITCH POINTS

Refer to the chapter on opening inwards


## DISMANTLING AND DISPOSAL

(CAME S.p.A. applies a certified Environmental Management System at its premises, which is compliant with the UNI EN ISO 14001 standard to ensure the environment is safeguarded.
Please continue safeguarding the environment. At CAME we consider it one of the fundamentals of our operating and market strategies. Simply follow these brief disposal guidelines:

- DISPOSING OF THE PACKAGING

The packaging materials (cardboard, plastic, and so on) should be disposed of as solid household waste, and simply separated from other waste for recycling.
Always make sure you comply with local laws before dismantling and disposing of the product.
DISPOSE OF RESPONSIBLY!

- DISMANTLING AND DISPOSAL

Our products are made of various materials. Most of these (aluminum, plastic, iron, electrical cables) are classified as solid household waste. They can be recycled by separating them before dumping at authorized city plants.
Whereas other components (control boards, batteries, transmitters, and so on) may contain hazardous pollutants.
These must therefore be disposed of by authorized, certified professional services.
Before disposing, it is always advisable to check with the specific laws that apply in your area.
DISPOSE OF RESPONSIBLY!

## CAME S.P.A.

Via Martiri Della Libertà, 15
31030 Dosson di Casier - Treviso - Italy
tel. (+39) 04224940 - fax. (+39) 04224941

